

# PhD studentship (Full-time)

Institution	Xi'an Jiaotong-Liverpool University, China
School	School of Advanced Technology
Supervisors	Principal supervisor: Professor Steven Guan (XJTLU)
	Co-supervisor: Dr Yutao Yue (JITRI)
	Co-supervisor: Professor Eng Gee Lim (XJTLU)
	Co-supervisor: Professor Prudence Wong (UoL)
Application Deadline	Open until the position is filled
Funding Availability	Funded PhD project (world-wide students)
Project Title	Machine consciousness based on multi-sensor fusion
	基于多传感器融合的机器意识研究
Contact	Please email Prof Steven Guan (steven.guan@xjtlu.edu.cn) and Dr Yutao Yue (yueyutao@idpt.org) with a subject line of the PhD project title

## **Requirements:**

The candidate should have a first class or upper second class honours degree, or a master's degree (or equivalent qualification) in Mathematics, physics, computer, automation and other related professional background (数学、物理、计算机、自动 化等相关专业背景)

Strong knowledge background in machine learning (有较强的机器学习领域知识背景)

Evidence of good spoken and written English is essential. The candidate should have an IELTS score of 6.5 or above, if the first language is not English. This position is open to all qualified candidates irrespective of nationality.

### Degree:

The student will be awarded a PhD degree from the University of Liverpool (UK) upon successful completion of the program.

### Funding:



This PhD project is a collaborative research project between XJTLU (http://www.xjtlu.edu.cn) at Suzhou and JITRI (Jiangsu Industrial Technology Research Institute) Institute of Deep Perception Technology (IDPT) at Wuxi. The student will be registered as an XJLTU PhD student but is expected to carry out the major part of his or her research at the Institute at Wuxi. The PhD studentship is available for three years subject to satisfactory progress by the student. The award covers tuition fees for three years (currently equivalent to RMB 80,000 per annum). In addition, during the period of undertaking main research at institute at Wuxi, the PhD candidate will be provided with monthly living

allowance at a standard RMB 3000-6000 by Institute of Deep Perception Institute.

# Project Description:

Please Provide a summary of the proposed research project in language comprehensible to someone outside your field. 请对研究课题加以简要概述。

Cameras can perceive the appearance, color, and shape information of objects in the environment and are widely used in object classification, object detection, object segmentation, object tracking and other fields. However, it has drawbacks in recognizing the distance and speed of an object. Radar (refers to millimeter-wave radar in this project) uses the Doppler principle to measure the distance and speed of the object, and is not affected by external factors in the weather. Therefore, the combination of camera and radar can realize the perception of all-round attributes of the object and can meet the needs of working in allweather conditions. At present, with the rapid development of deep learning technology, multisensor fusion has attracted more and more attention. However, the technology of radarcamera fusion is far from mature, especially the multi-modal object association, object detection and tracking technology in the moving environment, which has also become a bottleneck restricting the wide application of radar-camera fusion technology. This project takes radar-camera fusion as the research object and conducts systematic research on the perception of the environment by the radar-camera, the processing and understanding of sensor information, and the mapping of perception information to the decision. Besides, this project applies the method of deep learning to the fusion of radar and camera to establish a unified deep learning model to analyze the data of radar and camera. In addition, this project will also be combined with actual scenarios to develop products of radar-camera integration in intelligent transportation, assisted driving, consumer electronics, security monitoring, robots and other industries.

摄像头可以感知所处环境中物体的外貌、颜色和形状信息,被广泛应用在目标分 类、目标检测、目标分割、目标跟踪等领域。然而,其在识别物体的距离和速度方面存 在缺陷。雷达(本课题指的是毫米波雷达)利用多普勒原理可以测得目标的距离和速 度,并且不受天气外界因素的影响。因此,摄像头和雷达的组合可以实现目标全方位属 性的感知和满足全天候工作的需求。目前,随着深度学习技术的快速发展,多传感器融 合也越来越受关注。但雷达-摄像头融合的技术远未成熟,特别是多模态的目标关联以 及运动环境中的目标的检测与跟踪技术,这也成为制约雷达-摄像头融合技术广泛应用 的瓶颈。本课题以基于多传感器融合的机器意识为研究对象,围绕雷达-摄像头对环境 的感知、传感信息的处理与理解、以及感知信息到决策映射等方面展开系统的研究。课 题将深度学习的方法应用于雷达-摄像头的融合,从而建立统一的深度学习模型来分析 雷达与摄像头的数据。本课题还将与实际场景结合起来,开发雷达-摄像头融合在智能 交通、消费电子、安全监控、机器人等行业里的产品。

For more information about doctoral scholarship and PhD programme at Xi'an Jiaotong-Liverpool University (XJTLU): Please visit

http://www.xjtlu.edu.cn/en/study-with-us/admissions/entry-requirements http://www.xjtlu.edu.cn/en/admissions/phd/feesscholarships.html

## Supervisor Profile:

**<u>Principal Supervisor</u>**: Steven Guan (Sheng-Uei Guan) received his BSc. from Tsinghua University and M.Sc. & Ph.D. from the University of North Carolina at Chapel Hill.

He is currently an Honorary Professor at University of Liverpool & also a Professor at Xi'an Jiaotong-Liverpool University (XJTLU). He served the head of department position at XJTLU for 4.5 years, creating the department from scratch and now in shape. Before joining XJTLU, he was a tenured professor and chair in intelligent systems at Brunel University, UK.



Prof. Guan has worked in a prestigious organization for several years, serving as a design engineer, project leader, and department manager. After leaving the industry, he joined the academia for three and half years. He served as deputy director for the Computing Center and the chairman for the Department of Information & Communication Technology. Later he joined the Electrical & Computer Engineering Department at National University of Singapore as an associate professor for 8 years.

Prof. Guan's research interests include: machine learning, computational intelligence, big data analytics, mobile commerce, modeling, networking, personalization, security, coding theory, and pseudorandom number generation. He has published extensively in these areas, with 140+ journal papers and 200+ book chapters or conference papers. He has chaired, delivered keynote speech for 100+ international conferences and served in 190 international conference committees and 20+ editorial boards.

### JITRI co-supervisor:

Dr. Yutao Yue received his Bachelor's degree of applied physics from University of Science and Technology of China, master and PhD degrees of computational physics from Purdue University of USA. He then served as team leader of Guangdong "Zhujiang Plan" 3rd Introduced Innovation Scientific Research Team, senior scientist and Chief Human Resources Officer of Shenzhen Kuang-Chi Group, etc.

His research interest include computational modeling and artificial intelligence, radar vision fusion, electromagnetic fields, etc. He has been engaged in frontier technology research and development and industrialization for 20 years. He has co-invented 354 granted Chinese patents, 18 USA patents, and 7 EU patents. He has led 6 major research projects with a total funding of nearly 150 million RMB. He has advised 13 postdoc research fellows, published over 20 papers, and received multiple awards including Wu Wenjun Artificial Intelligence Science and Technology Award. He has been received by General Secretary Xi Jinping due to outstanding achievements.

### How to Apply:

Interested applicants are advised to email Steven.Guan@xjtlu.edu.cn and yueyutao@idpt.org the following documents for initial review and assessment (please put the project title in the subject line).

- CV
- Two reference letters with company/university letterhead
- Personal statement outlining your interest in the position
- Proof of English language proficiency (an IELTS score of 6.5 or above)
- Verified school transcripts in both Chinese and English (for international students, only the English version is required)
- Verified certificates of education qualifications in both Chinese and English (for



international students, only the English version is required)

• PDF copy of Master Degree dissertation (or an equivalent writing sample) and examiners reports available